

# Radon and Mojette Projections' Equivalence for Tomographic Reconstruction using Linear Systems

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## Context

Medical or industrial CT scanner :

- Measures of X-Rays attenuation through an object
- 1D projection of the object
- 2D slice reconstructed using Radon theorem

Radon Theorem [Radon, 1919]:

- Defined in continuous domain
- Images are in discrete domain  $\Rightarrow$  approximations

Two approaches :

- Improve reconstructed image quality
- Directly implement discrete reconstructions

## Plan

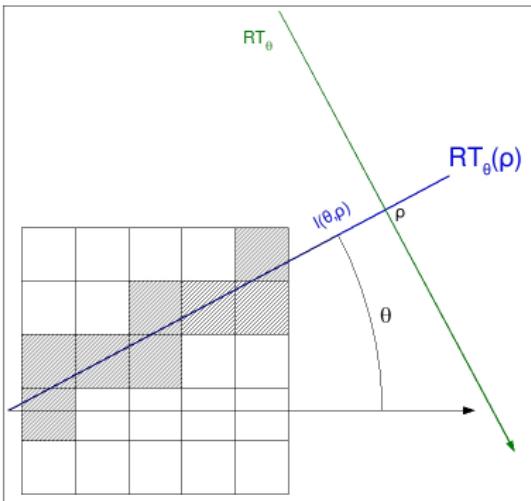
- Introduce the Radon theorem (discrete implementation and limitations)
- Present the Mojette transform (discrete transform, exact reconstruction, different from CT scan acquisition)
- Modelisation of the Radon acquisition to make it compatible with Mojette reconstruction

# The Radon Transform [Radon, 1919]

## Discrete Radon Transform and Retroprojection

$$RT_{\theta}(\rho) = \sum_{k=-\infty}^{+\infty} \sum_{l=-\infty}^{+\infty} I(k, l) \text{kernel}(\rho - k\cos\theta + l\sin\theta)$$

$$I'(k, l) = \sum_{\theta=0}^{\pi} \sum_{\rho=-\infty}^{\infty} RT_{\theta}(\rho) \text{kernel}(\rho - k\cos\theta + l\sin\theta)$$



## from Radon Transform to Sinogram

- $RT_{\theta}(\rho)$  is a projection value

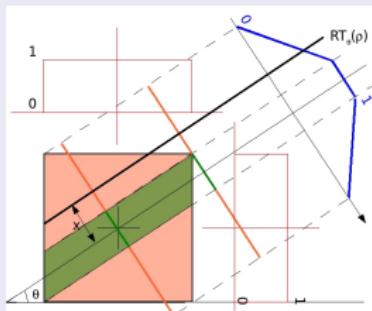
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### Usual Kernels

- Dirac Impulse
- B-Spline 0 Kernel :



### from Radon Transform to Sinogram

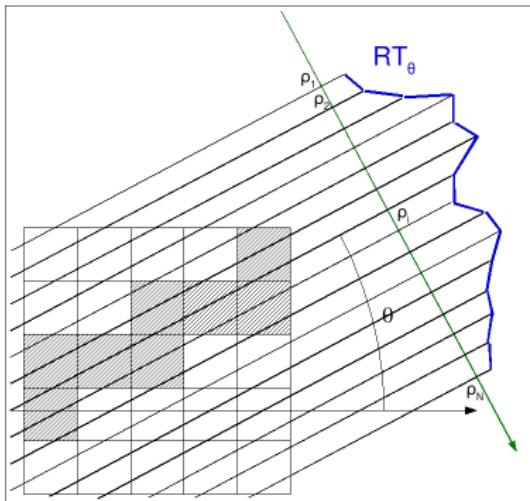
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# The Radon Transform [Radon, 1919]

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### from Radon Transform to Sinogram

- $RT_{\theta}(\rho)$  is a projection value
- A set of  $N\rho$  is the projection  $RT_{\theta}$  following  $\theta$  :

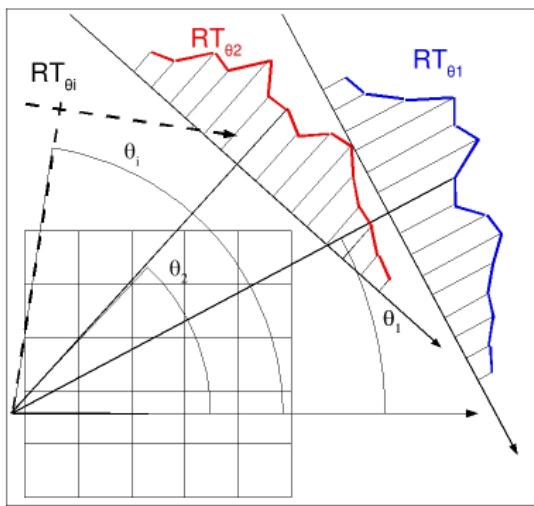
$$RT_{\theta} = \{RT_{\theta}(\rho_1), RT_{\theta}(\rho_2), \dots, RT_{\theta}(\rho_{N_{\rho}})\}$$

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- A set of  $N\theta$  projections is a sinogram  $S$  :

$$S = \{RT_{\theta_1}, RT_{\theta_2}, \dots, RT_{\theta_{N_{\theta}}}\}$$

## Discrete Radon Transform and Retroprojection

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↓  
S ( $N\theta = 180$ ,  $N\rho = 363$ )



### from Radon Transform to Sinogram

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- Exemple from Shepp-Logan Phantom image [L. Shepp and B. Logan, 1974]

## Discrete Radon Transform and Retroprojection

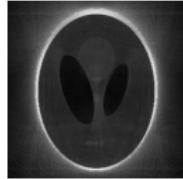
$$RT_{\theta}(\rho) = \sum_{k=-\infty}^{+\infty} \sum_{l=-\infty}^{+\infty} I(k, l) \text{kernel}(\rho - k\cos\theta + l\sin\theta)$$

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Reconstruction :

- Acts as a low-pass filter



BFP :

- Filtered projections
- Increase artefacts

## from Radon Transform to Sinogram

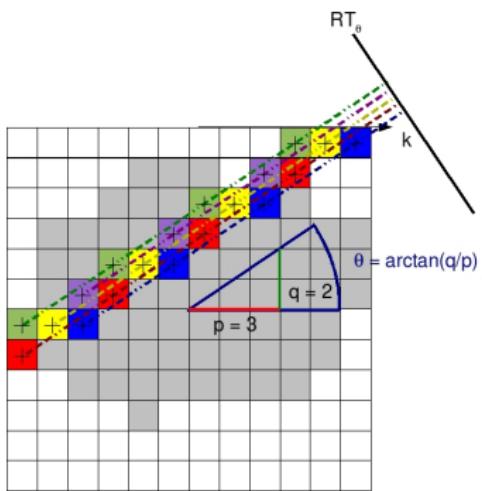
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- Exemple from Shepp-Logan Phantom image [L. Shepp and B. Logan, 1974]
- Retroprojection Results

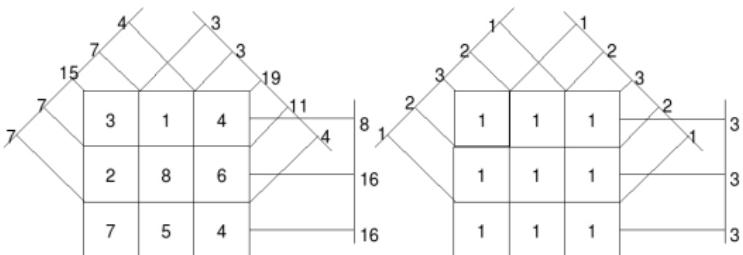


## Mojette Transform

- Discrete angles :  $(p, q) : \theta = \arctan \frac{q}{p}$
- $\text{GCD}(p, q) = 1, q > 0$  unless  $p = 1$  and  $q = 0$
- On a projection line : only pixels crossed by their center

## Definition

$$\text{Moj}_{(p,q)}(b) = \sum_{-\infty}^{+\infty} \sum_{-\infty}^{+\infty} \mathcal{I}(k, l) \Delta(b - kp + lq)$$

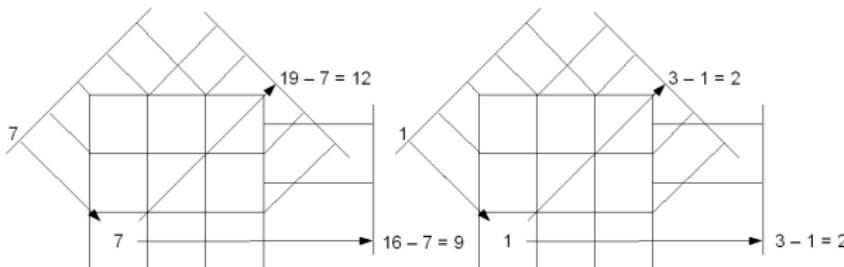


## Remarks

- $d\theta$  not constant
- $N_\rho$  and  $d\rho$  depend on  $(p, q)$
- Unary sinogram

## Iterative Principle of Mojette backprojection

- Each pixel is considered only one time on each projection
- Univoque correspondence between a bin and a pixel
- Pixel reconstructed
- Pixel value subtracted on each projection



## Remarks

- Exact Reconstruction (if  $\mathcal{P} = \{(p_i, q_i), i \in \mathbb{N}\}$  verify Katz criterion [Katz, 1969])
- $\mathcal{P} = \{(p_i, q_i), i \in \mathbb{N}\}$  can be computed by the Farey series.

## Differences between Radon and Mojette

The Radon Transform :

- same  $N\rho$  on each projection, and same sampling  $\delta_\rho$
- Constant angle step  $\delta_\theta$
- Ideal in CT scan, but approximative in discrete domain

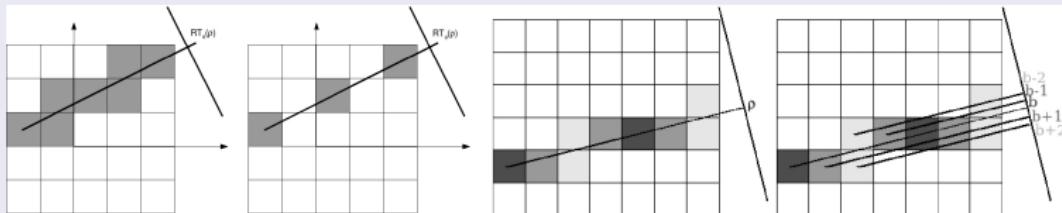
The Mojette Transform :

- Number of bins depends on  $(p, q)$
- $\delta_\theta$  variable
- Exact reconstruction in discrete domain

## Radon sinogram compatible with Mojette backprojection

- 1 : Projection angles in Radon acquisition  $\Leftrightarrow$  Mojette angles
- 2 :  $N_\rho$  and  $\delta_\rho$  in Radon acquisition depends on  $(p, q)$
- The RT acquisition is piloted by a set of couples  $(p, q)$  (Farey series)

## Line decomposition



$RFT_\theta(\rho)$  can be expressed as a linear combination of Mojette bin values

$$RFT_\theta(\rho) = \sum_{i=0}^{N_p} B_{p,q}^0(b_i, b) \cdot Moj_{p,q}(b_i)$$

$\theta = \arctan \frac{q}{p}$  and  $b \Leftrightarrow \rho$  and  $B_{p,q}^0(b_i, b)$  = coefficient between two bins  $b_i$  and  $b$

## Linear System

$$\left\{ \begin{array}{l} RFT_\theta(1) = \sum_{i=0}^{N_p} B_{p,q}^0(b_i, 1) \cdot Moj_{p,q}(b_i) \\ \dots \\ RFT_\theta(N\rho) = \sum_{i=0}^{N_p} B_{p,q}^0(b_i, N\rho) \cdot Moj_{p,q}(b_i) \end{array} \right.$$

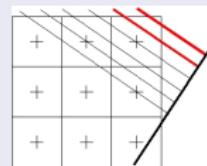
- $RFT_\theta(\rho_i)$  : value of sample  $\rho_i$  on projection  $\theta = \arctan \frac{q}{p}$  acquired with RFT
- $Moj_{p,q}(b_i)$  : Mojette bin  $b_i$  sought value



## Resolution not assured

- $N_p$  sought values ( $Moj_{p,q}(b_i)$ )
- $N_p$  acquired values
- But some cases give infinity of solutions

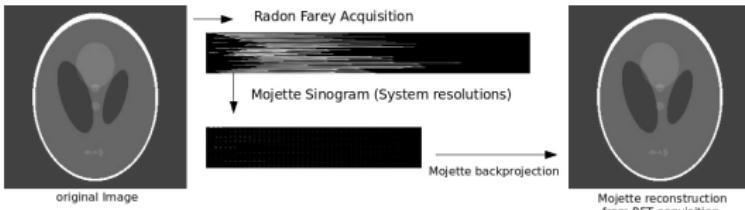
Add omitted lines



$$n(p, q) = \lceil \frac{(|p| - |q|) \cdot \sqrt{(p^2 + q^2)}}{2p} \rceil$$

## Triangular System

$$\left\{ \begin{array}{l} Moj_{p,q}(0) = \frac{RFT_\theta(-n)}{\alpha_{p,q}(-n,0)} \\ Moj_{p,q}(1) = \frac{RFT_\theta(-n+1) - Moj_{p,q}(0) \cdot \alpha_{p,q}(-n+1,0)}{\alpha_{p,q}(-n+1,1)} \\ \dots \quad \dots \\ Moj_{p,q}(j) = \frac{RFT_\theta(j-n) - \sum_{k=j-2n \geq 0}^{k < j} Moj_{p,q}(k) \cdot \alpha_{p,q}(j,k)}{\alpha_{p,q}(j-n,j)} \end{array} \right.$$



## Exact Reconstruction but not adapted to a real acquisition (CT scan)

- Possible to modify angle step  $\delta_\theta$  between each projection
- Impossible to change  $N_\rho$  on a projection

Our purpose :

- $N_\rho$  constant for the acquisition
- Interpolations to recover *RFT* projections from a “Uniform” *RFT* acquisition

## Remarks

- (*odd, odd*) projections always give false interpolation results
- For all (*even, odd*) and (*odd, even*) projections :

$$\exists N_0, \forall N_\rho \geq N_0 = 2\sqrt{2} \max\{N_\rho(p_i, q_i), (p_i, q_i) \in \mathcal{P}\} \text{ all interpolations are exact}$$

- In a real acquisition line (discrete pixels  $\neq$  continuous data) ?